

Description

MACHINE CONTROL APPARATUS AND METHOD

Technical Field

- [01] The present invention relates generally to an apparatus for controlling a machine and, more particularly, to an apparatus and method for controlling a machine using a movable interface module.

Background

- [02] A variety of machines include operator interface modules that are provided with various actuating devices to enable a machine operator to engage and disengage various elements of the machine. For example, industrial work machines such as hydraulic excavators typically include clusters of switches, indicators, and other devices positioned for convenient use by an operator to control the various functions associated with the excavator. Quite commonly, such interface modules are integrated into an armrest associated with an operator seat. Such an arrangement facilitates ready access by the operator in a functionally efficient manner.
- [03] One example of a machine having such an operator interface can be seen in United States patent 5,938,282 issued on 17 August 1999 to Agco GmbH & Co. This patent discloses a control device for use with a vehicle. The control device is located on and near the front of the armrest of an operator's seat and includes control members to control various functions of the vehicle.
- [04] Similar operator interface modules can be used with other machines and vehicles that include an operator seat, for example, agricultural tractors, various types of earthmoving equipment, aircraft, lift trucks, and motorized personal vehicles such as wheelchairs and golf carts.

[05] Because these operator interface modules are mounted on and associated with an armrest which is typically part of or mounted adjacent to the operator seat, they are conveniently positioned for comfortable and efficient use by the operator. However, they also may often be in the way of the operator or maintenance personnel under certain circumstances. Likewise, because these interface modules may extend in various directions from the operator armrest, they may be subject to damage at times when they are not being used to control the machine.

[06] The present invention is directed to overcoming one or more of the problems set forth above.

Summary of the Invention

[07] In a first aspect of the present invention, a device is provided for controlling selected functions of a machine. The machine includes a seat having at least one armrest supportably positionable adjacent to the seat. An interface module has a connecting portion connectable to the armrest and adapted to shift a working portion laterally between a retracted and extended position.

[08] In a second aspect of the present invention, a method is provided for controllably interacting with a machine having a seat and at least one armrest supportably positionable adjacent to the seat. The method includes the steps of providing an interface module having a connecting portion and a working portion, in which the connecting portion is connected to the armrest. The method further includes the steps of selecting an interface module working portion stored mode by moving the interface module working portion laterally toward the armrest until the working portion is at least partially concealed by the armrest, and selecting an interface module working portion working mode by moving the interface module working portion laterally away from the armrest until the working portion is substantially free from obstruction by the armrest.

Brief Description of the Drawings

- [09] Fig. 1 is a plan view of a machine suitable for use with an embodiment of the present invention;
- [10] Fig. 2 is a top view of an exemplary embodiment of the present invention;
- [11] Fig. 3 is a more detailed top view of the embodiment illustrated in Fig. 2;
- [12] Fig. 4 is a side view of a particular exemplary embodiment of the present invention;
- [13] Fig. 5 is a side view of another exemplary embodiment of the present invention;
- [14] Fig.s 6 through 8 are top views of three exemplary embodiments of the present invention.

Detailed Description

- [15] An exemplary embodiment of a machine 10 is illustrated in Fig. 1, the machine 10, for example, an earthmoving machine such as a hydraulic excavator, includes an operator station 11. The operator station 11 includes a seat 14 arranged as is customary to position an operator appropriately for controlling the machine 10.
- [16] As illustrated in Fig. 2, the seat 14 is provided with armrests 16, 18 that are supportably positionable adjacent to the seat 14. The armrests include upper surface portions 20 and lower surface portions 22. The armrests 16, 18 are typically integral with the seat 14 but, in some configurations, may be separate from the seat 14. In either instance, the armrests 16, 18 are positioned at such a location and in such an orientation as to provide convenient support for an operator's arms.
- [17] As is also shown in Fig. 2, a device 12 for controlling selected functions of the machine 10 is provided in cooperative arrangement with at least

one of the armrests 16, 18. In the exemplary embodiment shown, the device 12 includes an interface module 24 having a connecting portion 26 and a working portion 28. The connecting portion 26 is connectable to at least one of the armrests 16, 18 in a manner sufficient to allow the working portion 28 to shift or pivot laterally between a retracted position 30 and an extended position 32 relative to the respective armrest 16, 18.

[18] The interface module 24 may include a plurality of actuating devices 42 that may be associated with respective machine functions. The actuating devices 42 may include any desired combination of switches, for example, pushbutton, lever, or rotary switches, and gauges or indicator lights. The switches or indicators may be associated with various elements of the machine 10 such that an operator is able to control the respective functions of the machine 10.

[19] The working portion 28 of the interface module 24 may include an upwardly convex generally ovoid surface 44 and the actuating devices 42 may be arranged on the surface 44 at respective locations selected to facilitate manual manipulation of the actuating devices 42 by an operator. This exemplary embodiment is selected to provide an ergonomically comfortable arrangement such that an operator's hand may fit comfortably on the ovoid surface 44 while the operator's arm is supported by an armrest 16, 18. In this position, the operator's fingers are positioned for ready manipulation of the actuating devices 42.

[20] As illustrated in Fig. 3, when in the retracted or stored position 30 the interface module working portion 28 is at least partially concealed by the armrest 16, 18, and in the extended or working position 32 the interface module working portion 28 is substantially free from obstruction by the armrest 16, 18.

[21] Fig. 4 illustrates an exemplary embodiment of the device 12 in which the working portion 28 may move or pivot laterally between the retracted and extended positions 30, 32 along a first plane 34 that extends generally

horizontally below the armrest lower surface portion 22. The first plane 34 is located at an elevational position sufficient that the working portion 28 is at least partially located below the armrest lower surface portion 22 when the working portion 28 is in the retracted position 30.

[22] The armrest lower surface portion 22 may advantageously include a blocking portion 36. The blocking portion 36 may extend outwardly from the lower surface portion 22 at a location sufficient to limit retraction of the interface module 24 to a predetermined amount, such that a portion of the interface module working portion 28 remains free from obstruction by the armrest 16, 18 even when the working portion 28 is in the retracted position 30. In the particular embodiment shown, the blocking portion 36 extends substantially perpendicularly outward (downward) from the lower surface portion 22, although any configuration sufficient to interrupt the lateral motion of the interface module 24 at a preselected retracted position could readily be employed.

[23] A modified embodiment of the device 12 is illustrated in Fig. 5, in which the armrest 16, 18 is modified to include a hollow region 38 located between the upper and lower surface portions 20, 22. In this embodiment, the interface module 24 may move or pivot laterally between the retracted and extended positions 30, 32 along a second plane 40 that extends generally horizontally through the hollow region 38 and at an elevational position sufficient that the interface module working portion 28 is at least partially located within the hollow region 38 when the working portion 28 is in the retracted position 30.

[24] The interface module connecting portion 26 includes a connecting mechanism 46 adapted to pivotally interconnect the connecting portion 26 and the armrest 16, 18. The connecting mechanism 46 may take various forms, some of which are illustrated in Figs. 6-8. Each of these Figs. illustrates a particular structural arrangement of a connecting mechanism 46, although other satisfactory arrangements may be employed as will be appreciated by one skilled in the art of such devices. For example, the interface module 24 could be slidably supported

on tracks or rails such that it could be shifted laterally between the retracted and extended positions 30,32 without pivoting.

[25] As illustrated in Fig. 6, the connecting mechanism 46 may include a pivot pin 48 connectably engageable with the interface module connecting portion 26 and the armrest 16, 18 along an axis of rotation 50 that is substantially perpendicular to the respective armrest surface portion 20, 22.

[26] As illustrated in Fig. 7, the interface module connecting mechanism 46 may include a linkage 52 having a first end portion 54 connectable to the interface module connecting portion 26 and a second end portion 56 connectable to the armrest 16, 18.

[27] The linkage 52 may include at least first and second link arms 58, 60. In the illustrative embodiment, each of the first and second link arms 58, 60 are spaced apart one from the other and have first end portions 62, 63 that are pivotally connectable to the interface module connecting portion 26 and second end portions 64, 65 that are pivotally connectable to the armrest 16, 18. The embodiment illustrated in Fig. 7 shows the first and second link arms 58, 60 having a pivot joint positioned between the respective end portions 62, 63, 64, 65, while the embodiment illustrated in Fig. 8 shows the first and second link arms 58, 60 as solid links.

[28] Regardless of the particular structural configuration, each of the illustrated embodiments of the connecting mechanism 46 are sufficient to pivotally interconnect the interface module connecting portion 26 and a respective armrest 16, 18. As one skilled in the art will immediately recognize, it is a simple matter of selecting appropriately configured interface modules 24 to provide either right hand or left hand configurations that may be associated with either a right hand or left hand armrest 16, 18, as may be desirable for a particular machine 10 configuration.

Industrial Applicability

- [29] The device 12 may be advantageously employed for controlling selected functions of a machine 10 in which an operator is typically seated at an operator station 11. It is desirable that the operator have a comfortable and efficient working environment and that the devices necessary to control the machine 10 be conveniently at hand.
- [30] With the operator seated and the operator's arm positioned along the armrest upper surface portion 20, the interface module 24 may be placed in a working mode by moving or pivoting it to the extended position 32. In this position, the operator's hand will naturally and comfortably be supportable by the ovoid surface 44 of the working portion 28 and the actuating devices 42 will be conveniently positioned for manipulation by the operator.
- [31] At those times when the operator has no need to access the actuating devices 42, the interface module 24 may be readily placed in a stored mode by moving or pivoting it to the retracted position 30 in which it is located at least partially beneath or within the armrest 16, 18. The blocking portion 36 may be constructed and positioned to limit retraction of the interface module 24 to whatever extent may be desired as appropriate for the particular machine 10. In the retracted position 30 the interface module 24 is both out of the way of the operator and of service and maintenance personnel and is protected from accidental damage. In this manner, the operator's station is well organized and space is used efficiently. At the same time, the interface module 24 may be quickly pivoted to the extended position when it is again desired to have access to the actuating devices 42.
- [32] As is apparent from the foregoing description, illustrated embodiments of the present invention provide a convenient, ergonomic, and efficient device 12 for controlling selected functions of a machine 10. Although the illustrated machine 10 is an earthworking machine such as a hydraulic excavator, the described device 12 may be successfully applied to any machine

having an operator's station, for example, a personal transport vehicle such as an automobile, golf cart, electric wheelchair, and to other machines such as aircraft and military equipment.

- [33] As will also be apparent to those skilled in the art, modifications and variations of the apparatus and method described above can be made without departing from the true scope of the invention. It is likely that other embodiments beyond those described above will become apparent to those skilled in the art after consideration of the foregoing specification. Consequently, it is intended that the specification, embodiment, and examples set forth above be considered as exemplary only, with the true scope of the invention defined by the appended claims and equivalents.